CHAITANYA GURUNATH KULKARNI

+1 (480)-868-4277 | cgkulkar@asu.edu | https://www.linkedin.com/in/chaitanya95/ | Portfolio - https://chaitanyakulkarni95.com/ Design Engineer with master's degree in Mechanical Engineering looking for full-time position & willing to relocate.

EDUCATION

Master of Science, Mechanical Engineering

May 2020

Arizona State University, Tempe, AZ

Bachelor of Engineering, Mechanical Engineering

July 2017

University of Pune, India

TECHNICAL SKILLS

CAD & CAE: SolidWorks, CATIA V5, AutoCAD, Creo, Pro - E, Autodesk Fusion 360, ANSYS, SolidWorks Simulation, 3DEXPERIENCE

Other Software & Applications: MS Office (Word, Excel, PowerPoint), G Suite, PLM, TeamCenter

Hands-On Experience: Injection Molding, 3D Printing, Sheet Metal, Stamping, Cutting, Drilling, Welding, Machining **Certifications/Training:** Geometric Dimensioning & Tolerancing (GD&T), Failure Mode & Effects Analysis (FMEA)

WORK EXPERIENCE

Design Engineer, Goken America, Dublin, OH

Feb'22 - Present

- Successfully completed DFM changes in cooling system design and its optimization using SolidWorks.
- Worked on the plastic part design and sheetmetal part design.
- Designed Body in White parts, GSD surfacing, part, assembly, and sheet metal modules extensively using CATIA V5.
- Developed various fixture designs and engineering drawings using Catia V5, SolidWorks, and ASME Y14.5 standards.

Development Engineer, Zimmer Biomet, Warsaw, IN

Jan'21 - Feb'22

- Responsible for maintaining the design & development of medical devices, implants, and packaging.
- Generated over 1200 quality documents in the span of a year by continuously improving the documentation process.
- Worked on various part designs & product specifications, design inputs & interactions, engineering drawings, Bill of Materials (BOM)
- Performed Critical to Quality (CTQ) assessment, Worst-Case Analysis (WCA), Dimensional Analysis & Geometrical Assessment, change management, risk management, verification & validation activities, 3D CAD models of parts & assemblies.
- Directed 20 Design Reviews and coordinated design review meetings for new product implementation.
- Continuous coordination with cross-functional teams like design, quality, R&D, regulatory, and vendors.

Mechanical Design Engineer, UVFAB Systems, Tempe, AZ

Oct'20 - Jan'21

Project: Design & Development of Conveyor Belt Surface Disinfection System Using Germicidal Ultraviolet (UV-C) Light

- Developed the system for food industries as per Design for Manufacturability (DFM) & Design for Assembly (DFA).
- Performed the flow & thermal simulations using SolidWorks Simulation, worked on patent writing & part drawings.
- Designed, developed & tested the mechanical components & assemblies from conception to production.

Design Engineer (Team Lead), Engineering Projects in Community Service (EPICS), Arizona State University, AZ

June'20 – Dec'20

- Project: Development of a Low-Cost Battery Module for a Powered Wheelchair (In collab with 'Wheelchair Labs')
- Identified, formulated & produced effective solutions to emerging problems, determined project flow & project management.
- Organized client meetings, worked on make or buy decisions, Lithium-ion cells, modules & different battery pack designs.
- Worked on mechanical designs and drafting, studied ASME Y14.5 standards, 3D CAD modeling & assembly using SolidWorks.
- Carried out structural strength & fatigue tests on the designed model using Finite Element Analysis (FEA).

Research Assistant, Neuromuscular Control and Human Robotics Laboratory (NCHRL), Arizona State University, AZ Aug'19 – Dec'19 Project: Development of an Autonomous Submersible Robot for Water Quality Inspection.

- Analyzed, optimized & validated the design by proposing new conceptual designs.
- Carried out 3D printing prototype tests to check reliability using Cura software & worked on the waterproofing of the model.

PATENTS/PUBLICATIONS

A Wearable Soft Robotic Medical Device to Treat Plantar Flexion Contractures in Brain Injuries

- Designed & modeled the device using SolidWorks, 3d printed the parts & built soft actuators using sewing machine & LASER cutting.
- Evaluated overall performance, reliability, safety & removed loopholes using Root Cause Analysis (RCA)
- The DON/DOFF time of the device was below 2 min, which is effective compared to other devices such as splints & serial casts Able to create a total angle displacement of around 22° which covers the normal angle range of PFC which is around 15°
- Published this research on US Patent & Trademark Office & Skysong Innovations.

Design of Amphibian Exploration Rover

- Proposed a unique cost-effective mechanism comprising hybrid wheels for traversing the rover on the ground as well as water
- Designed & modeled hybrid wheels using SolidWorks, carried out Computational Fluid Dynamics (CFD) analysis using ANSYS Fluent
- 3D printed & fabricated all the parts, waterproofed all the components, calculated the efficiency of hybrid wheels around 82%
- Got patent from IP Office, Mumbai, India (Patent No: 201721018524).